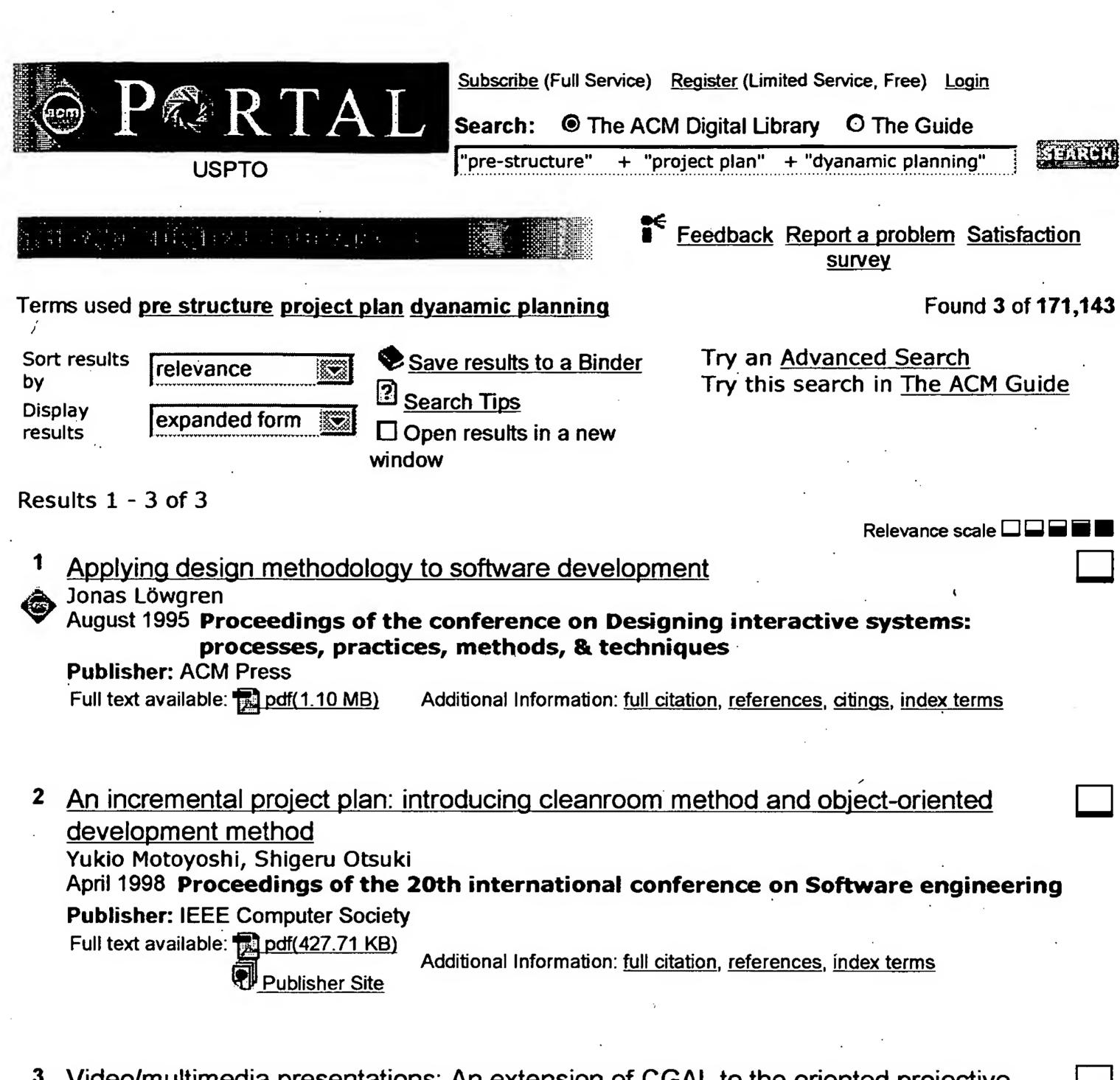
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4	BRS	L4	0	(dynamic adj plan\$4) and (project\$4 near activ\$4)
5	BRS	L5	2	(dynamic adj plan\$4) and (project adj plan)
6	BRS	L6	128	(project adj plan) same (activit\$4)
7	BRS	L7	86	((project adj plan) same (activit\$4)) and (structur\$4 same gener\$4)
8	BRS	L8	0	((project adj plan) same (activit\$4)) and (structur\$4 same gener\$4) and (pre adj structu\$4)
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3 Video/multimedia presentations: An extension of CGAL to the oriented projective

plane T2 and its dynamic visualization system

A. G. Oliveira, P. J. de Rezende, F. P. Selmi-Dei

June 2005 Proceedings of the twenty-first annual symposium on Computational geometry

Publisher: ACM Press

Full text available: pdf(123.91 KB) Additional Information: full citation, abstract, references, index terms

The oriented projective plane T² is an extension of the Euclidean plane E² and comprises a number of advantages for algorithm design and implementation. We have extended the Computational Geometry Algorithms Library (CGAL) to allow for the implementation of geometric primitives and algorithms. The present video illustrates both the extension of a few algorithms to T² under CGAL and a dynamic visualization system (T² Viewer)built specially for displayin ...

Keywords: CGAL, algorithm animation, oriented projective plane, visualization



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15	BRS	L15	2	(first adj policy) same (second adj policy) a (plan\$3) and model\$3 and buffer\$3	
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18	BRS	L18	16	((construction) same model\$) and (construction same (project adj plan\$3))	
19	BRS	L19	8	((construction) same model\$) and (construction same (project adj plan\$3)) and criteria	
20	BRS	L20	0	(construction same (project adj plan\$3)) and (project adj plan\$3 same buffer\$3)	
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24	BRS	L24	0	(project adj plan\$3 same buffer\$3) and update and activity and gui	

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